SPASS: Combining Superposition, Sorts and Splitting

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Bibliography

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- A Theory of Resolution L. Bachmair and H. Ganzinger Handbook of Automated Reasoning
- A Machine Oriented Logic Based on the Resolution Principle J.A. Robinson, JACM 1965

General

- The unsatisifiability problem for FOL is undecidable
 - No terminating algorithm which says yes ↔ the formula is non satisfiable
- The unsatisfiability problem is enumerable
- Resolution is such enumeration procedure
- Implemented in Otter, Spass, Bliksem, Vampire, ...
- Succeed in proving interesting theorems
 Adapts to certain decidable logics
- But predictability is an issue
- Limited practical usage

Clauses

- A literal is an atom or its negation

 positive literal = atom
 negative literal = negated atom
- A clause is a finite multiset of literals
- The meaning of {A₁, A₂, ..., A_n} is: $\forall X_1, X_2, ..., X_n$: (A₁ \lor A₂ \lor ... A_n)
- The goal is to refute a given finite set of clauses
- Prove that $C_1 \wedge C_2 \dots \wedge C_n \rightarrow D$ by refuting $\{C_1, C_2, \dots, C_n, \neg D'\}$

Unifying Terms

- Substitution: A mapping σ from the set of variables to the terms such that Xσ≠X only for finitely many X
- Generalizes to terms and literals
- σ is a matcher for terms s and t if s $\sigma = t$
- σ is a unifier for terms s and t if s σ = t σ
- σ is the most general unifier (mgu) of s and t if:
 - It is a unifier of s and t
 - For every unifier τ of s and t there exists a substitution λ such that $\lambda \sigma = \tau$

Examples

| Term 1 | Term 2 | Unifier |
|---------------|------------|---|
| а | Х | {X ↦ a} |
| p(a, X) | p(Y, b) | ${X \mapsto b, Y \mapsto a}$ |
| p(f(X), g(Z)) | p(f(a), Y) | $\{X \mapsto a, Y \mapsto g(Z)\}$ |
| p(f(X), g(Z)) | p(f(a), Y) | ${X\mapsto a, Y\mapsto g(a), Z\mapsto a}$ |
| | | |
| | | |

Resolution

- C and D clauses w/o overlapping variables
- $\varnothing \neq P \subseteq C$ with positive literals
- $\varnothing \neq N \subseteq D$ with negative literals
- There exists a substitution $\boldsymbol{\sigma}$

$$- P \sigma = \{A\}$$

$$- \mathsf{N} \sigma = \{\neg \mathsf{A}\}$$

• Then: ((C -P) $\tau \cup$ (D - N) τ)

- where $\tau = mgu(P, N)$

Example

1:{¬p(X, Y), p(Y, X)} 2:{¬p(X, Y), ¬ p(Y, Z), p(X, Z)} 3: {p(X, f(X))} 4: {¬p(a, a)}

Resolution and Factoring

- Two types of resolution
 - Unify literals within one clause (factoring)
 - Unify literals within different clauses
- Advantage of separation
 - Reduce the cost of resolution
 - Reduce the size of clauses

Resolution



Factoring

$$I \qquad \frac{\Gamma \rightarrow \Delta, A, B}{(\Gamma \rightarrow \Delta, A)\sigma}$$

$$\sigma = mgu(A, B)$$

$$I \qquad \frac{\Gamma, A, B \rightarrow \Delta}{(\Gamma, A \rightarrow \Delta) \sigma}$$

1: {p(X), p(Y)} 2: {¬p(X), ¬P(Y)}

Observation

- Simple resolution is easy to implement but does not get very far
- Often diverges due to the inherent complexity of the problem of finding a proof
 - Large possibly infinite search space
- Theorem provers implement refinements (restrictions) to resolution

Refinements of resolution

- Block certain clauses
 - Subsumption & Weight strategies
- Block certain literals in a clause

 Ordering
- Impose a structure on the resolution
 - Hyperresolution
 - Linear resolution

A refinement is **complete** if every unsatifiable set of clauses has a derivation of the empty clause \Box

Subsumption

- Blocks complete clauses from being considered
- If two clauses C and D exist such that $C \subseteq D$ then any conclusion from D can also be obtained from C
- Becomes even more important with equality

Subsumption Deletion

$$R \xrightarrow{\Gamma_1 \to \Delta_1} \qquad \begin{array}{c} \Gamma_2 \to \Delta_2 \\ \\ \Gamma_1 \to \Delta_1 \\ \\ \Gamma_1 \sigma \subseteq \Gamma_2 \\ \\ and \\ \\ \Delta_1 \sigma \subseteq \Delta_2 \end{array}$$

A Saturation Based Theorem Prover

- Start with an initial set of clauses
- Apply rules and add more clause until either
 No more clauses can be derives (saturation)
 - The set of clauses is saturated w.r.t. to the inference rules
 - The empty clause \Box is derived (refutation)

Simple SPASS rules

$$R \xrightarrow{\Gamma_{1}, A \to \Delta_{1}}{\Gamma_{2} \to \Delta_{2}, B}$$

$$I \xrightarrow{\Gamma_{1}, \Gamma_{2} \to \Delta_{1} \Delta_{2} \sigma} \sigma = mgu(A, B)$$

$$I \xrightarrow{\Gamma \to \Delta, \Delta, B}{(\Gamma \to \Delta, A)\sigma}$$

$$I \xrightarrow{\Gamma, \Delta, B \to \Delta}{(\Gamma, A \to \Delta) \sigma}$$

$$R \xrightarrow{\Gamma_{1} \to \Delta_{1}}{\Gamma_{2} \to \Delta_{2}}$$

$$R \xrightarrow{\Gamma_{1} \to \Delta_{1}}{\Gamma \to \Delta}$$

A Simple Resolution Based TP

- A worklist algorithm
- Remember which inference rules have been tried
- Prefer reductions over inferences
- Prefer small clauses

A Simple Resolution Based TP



A Simple Example

1: → p(f(a))2: p(f(X) → p(X))3: p(f(a)), p(f(X))

Fair selection

- ResutionProver1 is complete when choose is fair
 No clauses stays in Us forever
- A simple fair selection
 - Chose the lightest clause smaller size
 - Finitely many clauses of a given size in a given vocabulary
- Unfair selection may also be useful
 - Ignore clauses which are too big
 - Restart few times with larger bounds

Maintained Invariants

- Any inference conclusion (resolution, factoring) from Wo is either a tautology or contained/subsumed by a clause in Wo, Us
- Wo and Us are completely inter-reduced

− taut(Wo \cup Us) = Wo \cup Us

- strictsub(Wo \cup Us, Wo \cup Us) = Wo \cup Us
- Partial correctness
 - Upon termination Wo is saturated or $\Box \in Us$

Other properties of ResolutionProver1

- In case a N' ⊆ N is known to be satisfiable, initialized with
 - − Wo := N';
 - Us' := (N N')
- The initial order of N may be important

Subsumption

- On non-trivial examples $|Wo| \ll |Us|$
- Subsumption test w.r.t. Us becomes the bottleneck (95%)

A Second Resolution Based TP

```
ResolutionProver2(N)
```

Wo := \emptyset ;

```
Us := taut(strictsub(N, N));
```

```
while (Us \neq \emptyset and \Box \notin Us) {
```

```
(Given, Us) = choose(Us);
```

```
if (sub(Given), Wo) \neq \emptyset) {;
```

```
Wo := sub(Wo, {Given});
```

```
Wo := Wo \cup{Given};
```

```
New := res(Given, Wo) \cup {Given};
```

```
New := taut(strictsub(New, New));
```

```
New := sub(New, Wo);
```

 $Us := Us \cup New; \qquad \}\}$

if (Us = \varnothing) then print "Completion Found";

If ($\Box \in Us$) then print "Proof found";

Maintained Invariants

- Any inference conclusion (resolution, factoring) from Wo is either a tautology or contained/subsumed by a clause in Wo, Us
- Wo is completely inter-reduced
 - taut(Wo) = Wo
 - strictsub(Wo, Wo) = Wo
- Partial correctness
 - Upon termination Wo is saturated or $\Box \in Us$

Ordering

- Block certain literals from consideration
- Impose an order < on literals
- Apply resolution/factoring only on maximal literals
- Drastically reduces the number of applied rules
- Completeness may be an issue
- Can guarantee termination for certain decidable class of logics

Resolution with ordering

σ=mgu(A, B)

A is maximal in Γ_1 , $A \rightarrow \Delta_1$

B is maximal in $\Gamma_2 \rightarrow \Delta_2$, B

Propositional example

- 1: {a, b}
- 2: {a, ¬b}
- 3: {¬a, b}
- 4: {¬a, ¬b}

a < b < ¬a < ¬b

Completeness

- In the propositional case any order results in a complete refinement (Theorem 2.7: De Nivelle)
- In predicate logic the situation is more complicated $C=\{p(X),\,q(X),\,r(X)\}$ where p(X)< q(X) < r(X) $D=\{\neg r(0)\}$
- An order is liftable if A < B implies A $\theta \le B \theta$
- An order < on literals is descending if
 - $A < B \Rightarrow A\theta_1 < B \theta_2$
 - A θ < A when θ is not a renaming of A
- For liftable and descending orders resolution is complete

Orders in Spass

- Knuth-Benedix Ordering (KBO)
 - Invented as part of the Knuth-Benedix completion algorithm
 - Based on orders on functions/predicates
 - Total order on ground terms
 - Useful with handling equalities
- Recursive path ordering with Status [Dershowitz 82]
 - Useful for orienting distributivity

Other rules in Spass

- Sort constraint resolution
- Hyperresolution
- Paramodulation
- Splitting

Missing

- The automatic Spass loop (Table 4)
- The overall loop with splitting (Table 7)
- Data structures and algorithms

Conclusion

- Resolution based decision procedures can prove interesting theorems
- Refinements of resolution are essential
- Decidability of certain classes of first order logic is possible
- Combing with specialized decision procedures is a challenge
- Other issues:
 - Scalability
 - Counterexamples